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ISSN No. (Print): 0975-1718 ISSN No. (Online): 2249-3247 A Common Fixed Point Theorem Using A-Compatible and S-Compatible Mappings

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ABSTRACT: The aim of this paper is to generalize common fixed point theorem proved by Bijendra singh by introducing the two types of weak reciprocally continuous mappings. The concepts of compatibility and complete metric space are replaced by two different types of weak reciprocally continuous mappings along with some weaker conditions.

Keywords: Fixed point, self maps, compatible mappings, weakly compatible, mappings, associated sequence, reciprocally continuous mappings, A- compatible mapping, S-compatible. Mapping, A-Weak reciprocally continuous mappings, S-Weak reciprocally continuous mappings,

AMS (2000) Mathematics Classification: 54H25, 47H10

I. INTRODUCTION

G. Jungck [1] introduced the concept of compatible maps which is weaker than weakly commuting maps. G.Jungck [1] generalized the concept of compatible mappings by introducing the notion of compatible mappings of type (A). Pathak extended the concept of compatibility to two analogus definitions namely A- compatible and S-compatible. After wards Jungck and Rhoades [4] defined weaker class of maps known as weakly compatible maps.

Pant [2] introduced a new notion of continuity namely reciprocal continuity for a pair of self maps and proved some common fixed point theorems. Further Pant [2] *et al* introduced the concept of weak reciprocally continuity.

1.1. 1 Definitions and Preliminaries Compatible mappings: Two self maps A and S of a metric space (X,d) are said to be compatible mappings [1] if $\lim_{n \to \infty} d(ASx_n, SAx_n) = 0$, whenever $\langle x_n \rangle$ is a sequence in X such that

 $\lim_{n\to\infty}Ax_n = \lim_{n\to\infty}Sx_n = t \text{ for some } t \quad X.$

1.1. 2 Weakly compatible mappings: Two self maps A and S of a metric space (X, d) are said to be weakly compatible [4] if they commute at their coincidence point. i.e. if Au=Su for some u X then ASu = SAu.

1.1.3 Reciprocally continuous mappings: Two self maps A and S of a metric space (X, d) are said to be reciprocally continuous [2] if $\lim_{n\to\infty} ASx_n = At$ and $\lim_{n\to\infty} SAx_n = St$ when ever $\langle x_n \rangle$ is a sequence such that $\lim_{n\to\infty} Ax_n = \lim_{n\to\infty} Sx_n = t$ for some $t \in X$.

1.1.4 Weak reciprocally continuous mappings: Two self maps A and S of a metric space (X, d) are said to be Weak reciprocally continuous [11] iff $\lim_{n\to\infty} ASx_n = At$ or $\lim_{n\to\infty} SAx_n = St$ when ever $\langle x_n \rangle$ is a sequence such that $\lim_{n\to\infty} Ax_n = \lim_{n\to\infty} Sx_n = t$ for some $t \in X$.

Now we define the weak reciprocally continuous mappings by introducing into two analogous definitions.

1.1.5 A-Weak reciprocally continuous mapping: Two self maps A and S of a metric space (X, d) are said to be A-Weak reciprocally continuous iff $\lim_{n\to\infty} ASx_n = At$ whenever $\langle x_n \rangle$ is a sequence such that $\lim_{n\to\infty} Ax_n = \lim_{n\to\infty} Sx_n = t$ for some $t \in X$.

for some $t \in X$.

1.1.7 A-Compatible mappings

Two self maps S and T of a metric space (X, d) are A-compatible iff $\lim d(ASx_n, SSx_n) = 0$, when ever $\langle x_n \rangle$ is a

sequence such that $\lim_{i \to \infty} Sx_n = \lim_{i \to \infty} Ax_n = t$ for some $t \in X$.

1.1.8 S-Compatible mappings

Two self maps S and T of a metric space (X, d) are S-compatible iff $\lim_{n \to \infty} d(AAx_n, SAx_n) = 0$, when ever $\langle x_n \rangle$ is a

sequence such that $\lim Sx_n = \lim Ax_n = t$ for some $t \in X$.

It is clear that every compatible pair is weakly compatible but its converse need not be true.

Singh and Chauhan [6] proved the following theorem.

2. Theorem (A): Let A, B, S and T be self mappings from a complete metric space (X, d) into itself satisfying the following conditions

 $A(X) \subseteq T(X)$ and $B(X) \subseteq S(X)$...(2.1.1)One of A B S or T is continuous (212)

$$\begin{bmatrix} d(Ax, By) \end{bmatrix}^2 \le k_1 \begin{bmatrix} d(Ax, Sx)d(By, Ty) + d(By, Sx)d(Ax, Ty) \end{bmatrix} \\ + k_2 \begin{bmatrix} d(Ax, Sx)d(Ax, Ty) + d(By, Ty)d(By, Sx) \end{bmatrix}$$
... (2.1.3)
where $0 \le k_1 + 2k_2 \le 1$ $k_1, k_2 \ge 0$

where $0 \ge \kappa_1 + 2\kappa_2 \le 1, \kappa_1, \kappa_2 \le 0$

The pairs (A, S) and (B, T) are compatible on X ...(2.1.4) Further if X is a complete metric space ...(2.1.5)

Then A, B, S and T have a unique common fixed point in X.

Now we use definition of associated sequence [10] that plays a vital role in proving our theorem

2.1 Associated Sequence: Suppose AB,S and T are self maps of a metric space (X, d) satisfying the condition (2.1.1) Then for an arbitrary $x_0 \in X$ such that $Ax_0 = Tx_1$ and for this point x_1 , there exist a point x_2 in X such that $Bx_1 = Sx_2$ and so on. Proceeding in the similar manner, we can define a sequence $\langle y_n \rangle$ in X such that $y_{2n} = Ax_{2n} = Ax_{2n} = Ax_{2n}$ Tx_{2n+1} and $y_{2n+1} = Bx_{2n+1} = Sx_{2n+2}$ for $n \ge 0$. We shall call this sequence as an "Associated sequence of x_0 "relative to the four self maps A, B, S and T.

Now we prove a lemma which plays an important role in our main Theorem.

2.2 Lemma: Let A, B, S and T be self mappings from a complete metric space (X, d) into itself satisfying the conditions (2.1.1) and (2.1.3) Then the associated sequence $\{y_n\}$ relative to four self maps is a Cauchy sequence in Х.

Proof: From the conditions (2.1.1), (2.1.3) and from the definition of associated sequence we have

$$\begin{bmatrix} d(y_{2n+1}, y_{2n}) \end{bmatrix}^2 = \begin{bmatrix} d(Ax_{2n+1}, Bx_{2n}) \end{bmatrix}^2 \leq k_1 \begin{bmatrix} d(Ax_{2n+1}, Sx_{2n+1}) & d(Bx_{2n}, Tx_{2n}) + d(Bx_{2n}, Sx_{2n+1}) & d(Ax_{2n+1}, Tx_{2n} \end{bmatrix} + k_2 \begin{bmatrix} d(Ax_{2n+1}, Sx_{2n+1}) & d(Ax_{2n+1}, Tx_{2n}) + d(Bx_{2n}, Tx_{2n}) & d(Bx_{2n}, Sx_{2n+1}) \end{bmatrix} = k_1 \begin{bmatrix} d(y_{2n+1}, y_{2n}) & d(y_{2n}, y_{2n-1}) + 0 \end{bmatrix} + k_2 \begin{bmatrix} d(y_{2n+1}, y_{2n}) & d(y_{2n+1}, y_{2n-1}) + 0 \end{bmatrix}$$

This implies

$$d(y_{2n+1}, y_{2n}) \le k_1 \ d(y_{2n}, y_{2n-1}) + k_2 [d(y_{2n+1}, y_{2n}) + d(y_{2n}, y_{2n-1})]$$

$$d(y_{2n+1}, y_{2n}) \le h \ d(y_{2n}, y_{2n-1})$$

where $h = \frac{k_1 + k_2}{1 - k_2} < 1$
For every int eger $p > 0$, we get

$$d(y_1, y_2) \le d(y_1, y_2) + d(y_2, y_2) + d(y_1, y_2) + d(y_2, y_2) = 0$$

For every int eger
$$p > 0$$
, we get

$$\begin{aligned} d(y_n, y_{n+p}) &\leq d(y_n, y_{n+1}) + d(y_{n+1}, y_{n+2}) + \dots + d(y_{n+p-1}, y_{n+p}) \\ &\leq h^n d(y_0, y_1) + h^{n+1} d(y_0, y_1) + \dots + h^{n+p-1} d(y_0, y_1) \\ &\leq \left(h^n + h^{n+1} + \dots + h^{n+p-1}\right) d(y_0, y_1) \\ &\leq h^n \left(1 + h + h^2 + \dots + h^{p-1}\right) d(y_0, y_1) \end{aligned}$$

Since h < 1, $h^n \to 0$ as $n \to \infty$, so that $d(y_n, y_{n+p}) \to 0$. This shows that the sequence $\{y_n\}$ is a Cauchy sequence in X and since X is a complete metric space, it converges to a limit, say $z \in X$.

The converse of the Lemma is not true, that is A, B, S and T are self maps of a metric space (X, d) satisfying (2.1.1) and (2.1.3), even if for any $x_0 \in X$ the associated sequence converges, the metric space (X, d) need not be complete. The following example establishes this.

2.3. Example: Let X = (0,1) with d(x,y) = |x - y|

$$Ax = Bx = \begin{cases} \frac{1}{6} & \text{if } 0 < x < \frac{1}{4} \\ \frac{1}{4} & \text{if } \frac{1}{4} \le x < \frac{1}{2} \end{cases} \qquad Sx = Tx = \begin{cases} \frac{1}{8} & \text{if } 0 < x < \frac{1}{4} \\ \frac{1}{2} - x & \text{if } \frac{1}{4} \le x < \frac{1}{2} \end{cases}$$

Then A(X) = B(X) = $\left\{\frac{1}{6}, \frac{1}{4}\right\}$ while S(X) = T(X) = $\left\{\left(\frac{1}{4}, 0\right] \cup \frac{1}{8}\right\}$ so that the conditions A(X) \subseteq T(X) and

 $B(X) \subseteq S(X)$ are satisfied. Clearly (X, d) is not a complete metric space. It is easy to prove that the associated sequence $Ax_0, Bx_1Ax_2, Bx_3, \dots, Ax_{2n}, Bx_{2n+1}, \dots$, converges to the point $\frac{1}{4}$ if $\frac{1}{4} \le x < \frac{1}{2}$, but X is not a complete

metric space.

Now we generalize the above Theorem (A) in the following form.

3. MAIN THEOREM

3.1 Theorem (B): Let A, B, S and T are self maps of a metric space (X, d) satisfying the conditions (i). $A(X) \subseteq T(X)$ and $B(X) \subseteq S(X)$

(ii)
$$\begin{bmatrix} d(Ax, By) \end{bmatrix}^2 \leq k_1 \begin{bmatrix} d(Ax, Sx) d(By, Ty) + d(By, Sx) d(Ax, Ty) \end{bmatrix}$$

+ $k_2 \begin{bmatrix} d(Ax, Sx) d(Ax, Ty) + d(By, Ty) d(By, Sx) \end{bmatrix}$
for all x,y in x where $0 \leq k_1 + 2k_2 < 1, k_1, k_2 \geq 0$

- (iii) The pair (A, S) is A-weak reciprocally continuous and A-compatible or
 - The pair (A, S) is S- weak reciprocally continuous and S compatible and
- (iv) The pair (B, T) is weakly compatible.
- (v) For any $x_0 \in X$ The associated sequence relative to four self maps A ,B, S and T such that the sequence Ax_0 , $Bx_1 Ax_2$, Bx_3 ,..., Ax_{2n} , Bx_{2n+1} ,.... converges to $z \in X$. as $n \to \infty$.

Then A, B, S and T have a unique common fixed point z in X.

Proof: Using the condition (v),

We have $Ax_{2n} \to z$, $Tx_{2n+1} \to z$, $Bx_{2n+1} \to z$, $Sx_{2n} \to z$ as $n \to \infty$ (3.1.1) Case 1:

Since S is weak reciprocally continuous then $\lim_{n \to \infty} SAx_{2n} \to Sz$

since the pair (A, S) is S compatible then $\lim_{n\to\infty} d(SAx_{2n}, AAx_{2n}) = 0$ giving that

$$\lim_{n \to \infty} SAx_{2n} = \lim_{n \to \infty} AAx_{2n} = Sz \qquad \dots \dots (3.1.2)$$

Put $x = Ax_{2n}$ $y = x_{2n+1}$ in condition (ii) we have

$$\left[d(AAx_{2n}, Bx_{2n+1}) \right]^2 \le k_1 \left[d(AAx_{2n}, SAx_{2n}) \ d(Bx_{2n+1}, Tx_{2n+1}) + d(Bx_{2n+1}, SAx_{2n}) \ d(AAx_{2n}, Tx_{2n+1}) \right]$$

+ $k_2 \left[d(AAx_{2n}, SAx_{2n}) \ d(AAx_{2n}, Tx_{2n+1}) + d(Bx_{2n+1}, Tx_{2n+1}) \ d(Bx_{2n+1}, SAx_{2n}) \right]$

letting $n \to \infty$ on both sides and u sin g the conditions (3.1.1), (3.1.2) then we get

$$[d(Sz,z)]^2 \le k_1 [d(Sz,Sz) \ d(z,z) + d(z,Sz) \ d(Sz,z)] + k_2 [d(Sz,Sz) \ d(Sz,z) + d(z,z) \ d(z,Sz)]$$

$$\begin{bmatrix} d(Sz, z) \end{bmatrix}^2 \le k_1 \begin{bmatrix} d(Sz, z) \end{bmatrix}^2$$

$$\begin{bmatrix} d(Sz, z) \end{bmatrix}^2 (1 - k_1) \le 0 \text{ sin } ce \ 0 \le k_1 + 2k_2 < 1, k_1, k_2 \ge 0 \text{ we have}$$

$$d(Sz, z) = 0 \text{ giving that } Sz = z$$

Put x = z, $y = x_{2n+1}$ in condition (ii) we have

$$\left[d(Az, Bx_{2n+1}) \right]^2 \le k_1 \left[d(Az, Sz) d(Bx_{2n+1}, Tx_{2n+1}) + d(Bx_{2n+1}, Sz) d(Az, Tx_{2n+1}) \right] + k_2 \left[d(Az, Sz) d(Az, Tx_{2n+1}) + d(Bx_{2n+1}, Tx_{2n+1}) d(Bx_{2n+1}, Sz) \right]$$

letting $n \to \infty$ on both sides and $u \sin g$ the conditions Sz = z, (3.1.1), then we get $\left[d(Az,z)\right]^2 \le k_1 \left[d(Az,z)d(z,z) + d(z,z)d(Az,z)\right] + k_2 \left[d(Az,z)d(Az,z) + d(z,z)d(z,z)\right]$ $\left[d(Az,z)\right]^2 \le k_2 \left[d(Az,z)\right]^2$ $\left(1-k_2\right) \left[d(Az,z)\right]^2 \le 0 \sin ce \ 0 \le k_1 + 2k_2 < 1, k_1, k_2 \ge 0 \text{ we have}$ d(Az,z) = 0 giving that Az = z Since $A(X) \subseteq T(X)$ implies there exists $u \in X$ such that z = Az = Tu.

To prove Bu = z, put x = z, y = u in condition (ii) we have $\begin{bmatrix} d(Az, Bu) \end{bmatrix}^2 \leq k_1 \begin{bmatrix} d(Az, Sz)d(Bu, Tu) + d(Bu, Sz)d(Az, Tu) \end{bmatrix} \\
+ k_2 \begin{bmatrix} d(Az, Sz)d(Az, Tu) + d(Bu, Tu)d(Bu, Sz) \end{bmatrix} \\
U \sin g Az = Sz = z, and z = Az = Tu we have \\
\begin{bmatrix} d(z, Bu) \end{bmatrix}^2 \leq k_1 \begin{bmatrix} d(z, z)d(Bu, z) + d(Bu, z)d(z, z) \end{bmatrix} \\
+ k_2 \begin{bmatrix} d(z, z)d(z, z) + d(Bu, z)d(Bu, z) \end{bmatrix} \\
\begin{bmatrix} d(Bu, z) \end{bmatrix}^2 \leq k_2 \begin{bmatrix} d(Bu, z) \end{bmatrix}^2 \\
\begin{bmatrix} (1-k_2) \begin{bmatrix} d(Bu, z) \end{bmatrix}^2 \leq 0 \text{ Since } 0 \leq k_1 + 2k_2 < 1, where \quad k_1, k_2 \geq 0 \text{ we have} \\
d(Bu, z) = 0 \text{ giving that } Bu = z \end{bmatrix}$

Hence we have Az = Sz = Bu = z. Since (B, T) is weakly compatible Btu = TBu this implies Bz = Tz

Now we prove
$$Bz = z$$

Put $x = x_{2n}$, $y = z$ in condition (ii) we have
 $[d(Ax_{2n}, Bz)]^2 \le k_1 [d(Ax_{2n}, Sx_{2n})d(Bz, Tz) + d(Bz, Sx_{2n})d(Ax_{2n}, Tz)] + k_2 [d(Ax_{2n}, Sx_{2n})d(Ax_{2n}, Tz) + d(Bz, Tz)d(Bz, Sx_{2n})]$

letting $n \to \infty$ on both sides and $u \sin g$ the conditions Tz = Bz, (3.1.1) then we get

$$\begin{bmatrix} d(z,Bz) \end{bmatrix}^2 \le k_1 \begin{bmatrix} d(z,z)d(Bz,z) + d(Bz,z)d(z,z) \end{bmatrix} \\ + k_2 \begin{bmatrix} d(z,z)d(z,z) + d(Bz,z)d(Bz,z) \end{bmatrix} \\ \begin{bmatrix} d(Bz,z) \end{bmatrix}^2 \le k_2 \begin{bmatrix} d(Bz,z) \end{bmatrix}^2 \\ (1-k_2) \begin{bmatrix} d(Bz,z) \end{bmatrix}^2 \le 0 \text{ Since } 0 \le k_1 + 2k_2 < 1, \text{ where } k_1, k_2 \ge 0 \text{ we have } \\ d(Bz,z) = 0 \text{ giving that } Bz = z. \\ Hence Bz = Tz = z \\ \text{Case2:} \\ \text{Since A is weakly reciprocally continuous then } \lim_{n \to \infty} ASx_{2n} \to Az \\ \sin ce the pair (A, S) \text{ is A compatible then } \lim_{n \to \infty} d(ASx_{2n}, SSx_{2n}) = 0 \text{ giving that } \\ \lim_{n \to \infty} SAx_{2n} = \lim_{n \to \infty} AAx_{2n} = Az \\ \dots (3.1.3) \\ \end{bmatrix}$$

Put $x = Sx_{2n}$ $y = x_{2n+1}$ in condition (ii) we have

$$\left[d(ASx_{2n}, Bx_{2n+1}) \right]^2 \le k_1 \left[d(ASx_{2n}, SSx_{2n}) \ d(Bx_{2n+1}, Tx_{2n+1}) + d(Bx_{2n+1}, SAx_{2n}) \ d(ASx_{2n}, Tx_{2n+1}) \right]$$

+ $k_2 \left[d(ASx_{2n}, SAx_{2n}) \ d(ASx_{2n}, Tx_{2n+1}) + d(Bx_{2n+1}, Tx_{2n+1}) \ d(Bx_{2n+1}, SSx_{2n}) \right]$

letting $n \to \infty$ on both sides and $u \sin g$ the conditions (3.1.1), (3.1.3) then we get $\begin{bmatrix} d(Az,z) \end{bmatrix}^2 \le k_1 \begin{bmatrix} d(Az,Az) \ d(z,z) + d(z,Az) \ d(Az,z) \end{bmatrix} + k_2 \begin{bmatrix} d(Az,Az) \ d(Az,z) + d(z,z) \ d(z,Az) \end{bmatrix}$

$$\begin{bmatrix} d(Az, z) \end{bmatrix} \le k_1 \begin{bmatrix} d(Az, z) \end{bmatrix} \begin{bmatrix} d(Az, z) \end{bmatrix}^2 (1 - k_1) \le 0 \text{ sin } ce \ 0 \le k_1 + 2k_2 < 1, k_1, k_2 \ge 0 \text{ we have} d(Az, z) = 0 \text{ giving that } Az = z$$

Since A(X)
$$\subseteq$$
 T(X) implies there exists $v \in X$ such that $z = Az = Tv$
Put $x = x_{2n}$, $y = u$
 $\left[d(Ax_{2n}, Bv)\right]^2 \leq k_1 \left[d(Ax_{2n}, Sx_{2n})d(Bv, Tv) + d(Bv, Sx_{2n})d(Ax_{2n}, Tv)\right]$
 $+ k_2 \left[d(Ax_{2n}, Sx_{2n})d(Ax_{2n}, Tv) + d(Bv, Tv)d(Bv, Sx_{2n})\right]$

letting $n \rightarrow \infty$ on both sides and $u \sin g$ the conditions Tv = Az = z and (3.1.1) then we get

$$\begin{split} \left[d(z, Bv) \right]^2 &\leq k_1 \left[d(z, z) d(Bv, z) + d(Bv, z) d(z, z) \right] \\ &+ k_2 \left[d(z, z) d(z, z) + d(Bv, z) d(Bv, z) \right] \\ \left[d(Bv, z) \right]^2 &\leq k_2 \left[d(Bv, z) \right]^2 \\ (1 - k_2) \left[d(Bv, z) \right]^2 &\leq 0 \text{ sin } ce \ 0 \leq k_1 + 2k_2 < 1, k_1, k_2 \geq 0 \text{ we have} \\ \left[d(Bv, z) \right] &= 0 \text{ giving that } Bv = z \end{split}$$

Since (B, T) is weakly compatible implies $BTv = TBv \Rightarrow Bz = Tz$

Now we prove Bz = zPut $x = x_{2n}$, y = z in condition (ii) we have

$$\begin{split} \left[d(Ax_{2n}, Bz) \right]^2 &\leq k_1 \left[d(Ax_{2n}, Sx_{2n}) d(Bz, Tz) + d(Bz, Sx_{2n}) d(Ax_{2n}, Tz) \right] \\ &+ k_2 \left[d(Ax_{2n}, Sx_{2n}) d(Ax_{2n}, Tz) + d(Bz, Tz) d(Bz, Sx_{2n}) \right] \\ letting \quad n \to \infty \text{ on both sides and } u \sin g \text{ the conditions } Tz = Bz, (3.1.1) \text{ then we ge} \\ \left[d(z, Bz) \right]^2 &\leq k_1 \left[d(z, z) d(Bz, z) + d(Bz, z) d(z, z) \right] \\ &+ k_2 \left[d(z, z) d(z, z) + d(Bz, z) d(Bz, z) \right] \\ \left[d(Bz, z) \right]^2 &\leq k_2 \left[d(Bz, z) \right]^2 \\ (1 - k_2) \left[d(Bz, z) \right]^2 &\leq 0 \text{ Since } 0 \leq k_1 + 2k_2 < 1, \text{ where } k_1, k_2 \geq 0 \text{ we have} \\ d(Bz, z) = 0 \text{ giving that } Bz = z. \\ Hence Bz = Tz = z \end{split}$$

 $B(X) \subseteq S(X)$ implies there exists $w \in X$ such that Bz = z = Sw. since the pair (A,S) is A compatible then $\lim_{n \to \infty} d(ASx_{2n}, SSx_{2n}) = 0$ implies d(ASw, SSw) = 0 implies ASw = SSw

implies Az = Sz = z.

Since Az = Bz = Sz = Tz = z, we get z in a common fixed point of A,B,S and T. The uniqueness of the fixed point can be easily proved.

3.2. Remark: From the example given above, clearly the pair (A, S) is S weak reciprocally continuous and S compatible and (B, T) is weakly compatible as they commute at coincident points $\frac{1}{4}$. But the pairs (A, S) and

(B,T) are not compatible and not reciprocally continuous.

For this, take a sequence $x_n = \left(\frac{1}{4} + \frac{1}{n}\right)$ for n 1, then $\lim_{n \to \infty} Ax_n = \lim_{n \to \infty} Sx_n = \frac{1}{4}$ and $\lim_{n \to \infty} ASx_n = \frac{1}{6}$

also $\lim_{n\to\infty} SAx_n = \frac{1}{4}$. So that $\lim_{n\to\infty} d(ASx_n, SAx_n) \neq 0$. Also note that none of the mappings are continuous and the

rational inequality holds for the values of $0 \le k_1 + 2k_2 < 1$, where $k_1, k_2 \ge 0$. Clearly $\frac{1}{4}$ is the unique

common fixed point of A, B, S and T.

3.3 Remark: Theorem (B) is a generalization of Theorem (A) by virtue of the weaker conditions such as S- weak reciprocally continuous and S compatible in the pair (A,S) and (B,T) is weakly compatible, which are weaker conditions than compatibility of the pairs (A, S) and (B, T) assumed in theorem (A); The continuity of any one of the mappings is being dropped and the convergence of associated sequence relative to four self maps A, B, S and T in place of the complete metric space assumed in theorem(A).

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